

A photograph of a large industrial facility, likely a refinery or chemical plant, with numerous tall distillation columns and complex piping. Thick white smoke or steam is rising from various points across the facility. The sky is a dramatic mix of orange, yellow, and grey, suggesting a sunset or sunrise. The overall scene conveys a sense of large-scale industrial activity and its environmental impact.

Beyond Inspections:

How Remote Monitoring is Altering Air Emission Measurements

NCASI Eastern Regional Meeting

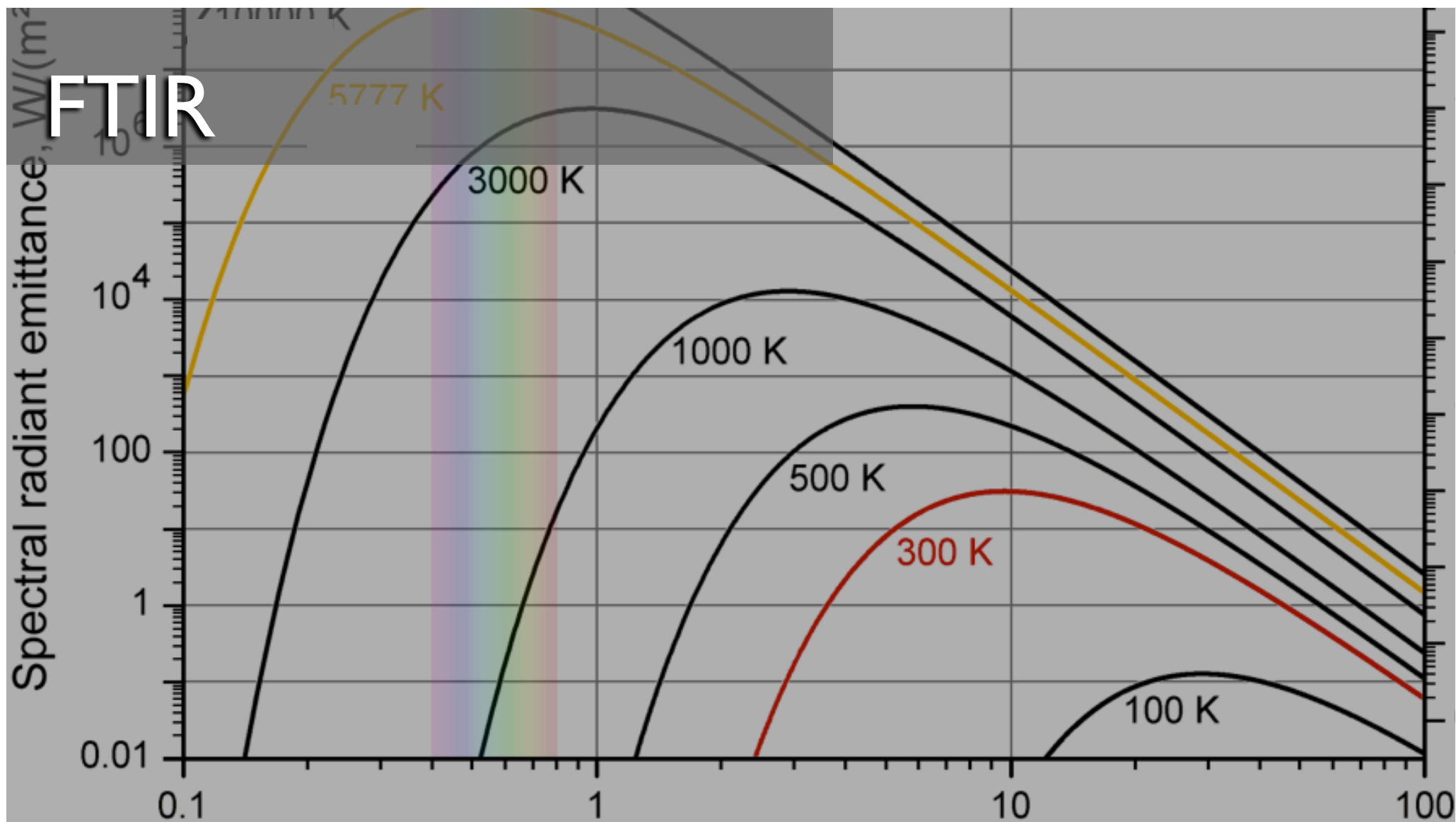
Atlanta, Georgia

June 4-6, 2018

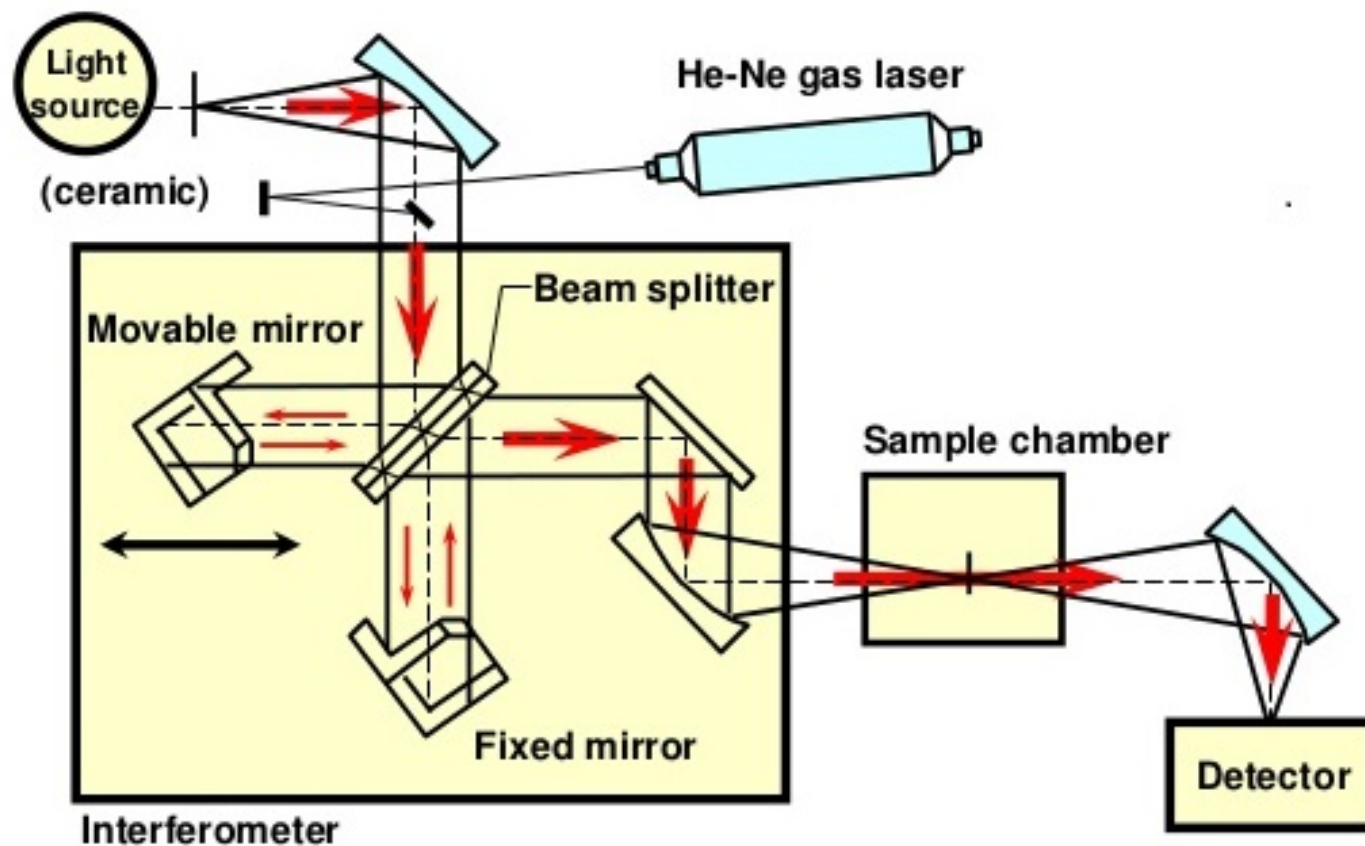
Jim Guenthoer, M.S.E, QSTI

Clean Air Engineering

FTIR

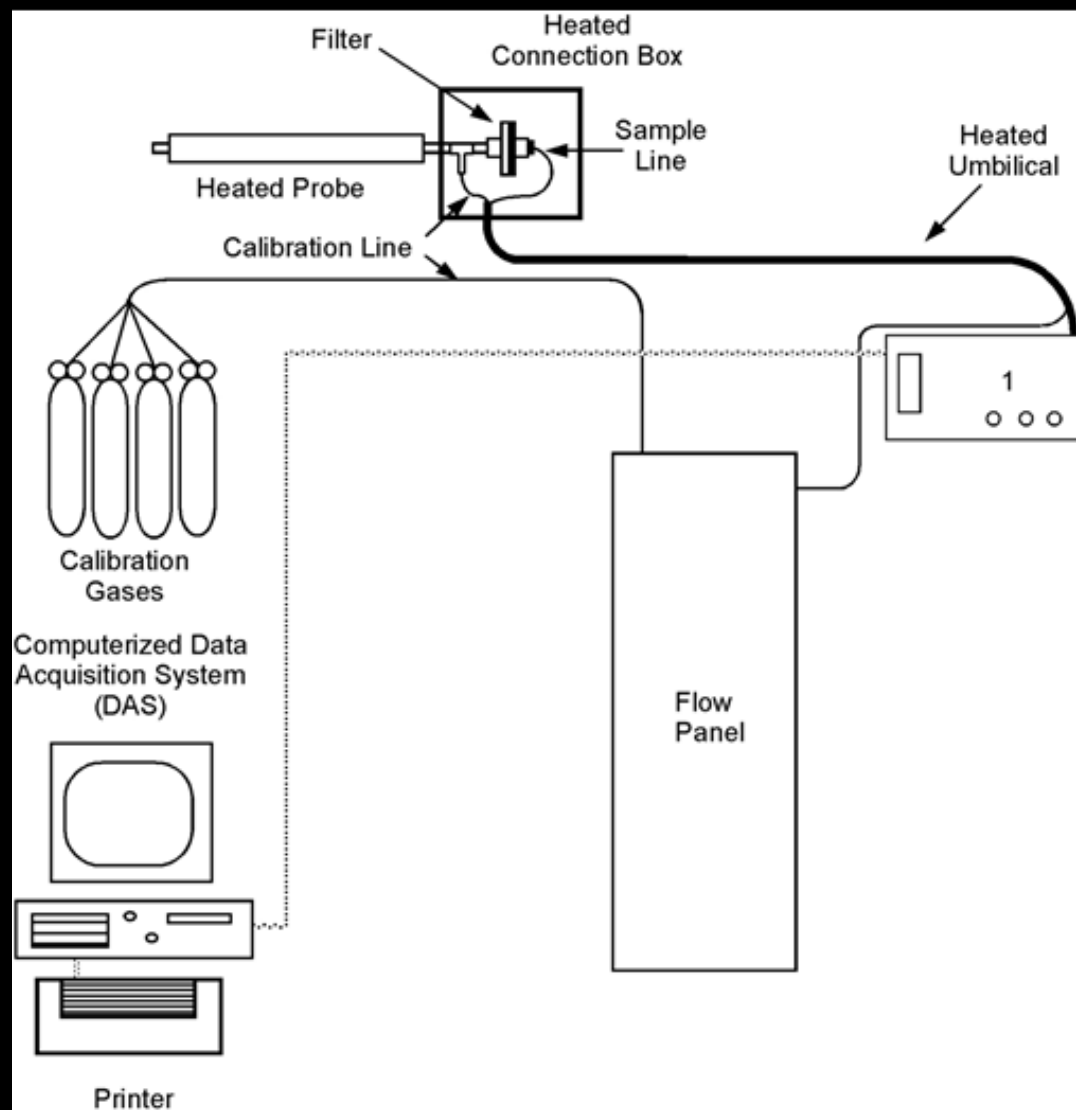


FTIR - WORKING



Extractive CEMS

EPA Method 320

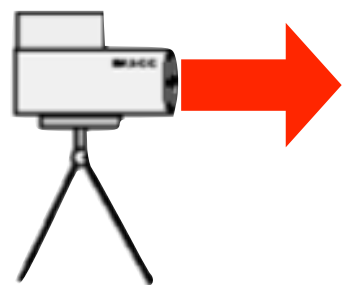


Open-Path FTIR Monitoring

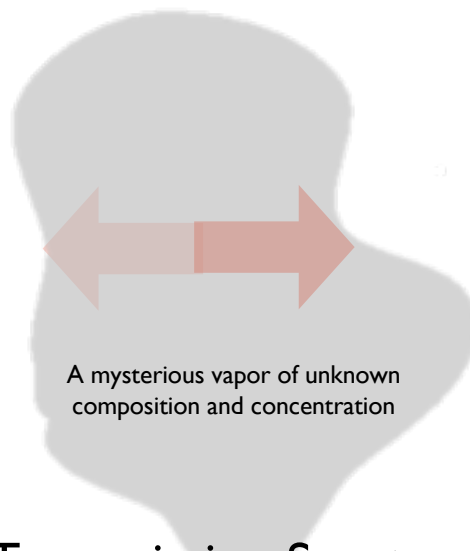
- Characterize fugitive emissions
- Multiple paths allow determination of plume size and direction of motion
- Low ppb detection limits on many compounds



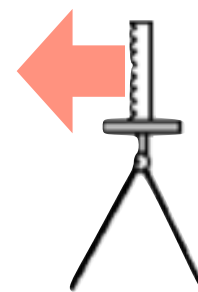
Open Path FTIR



FTIR

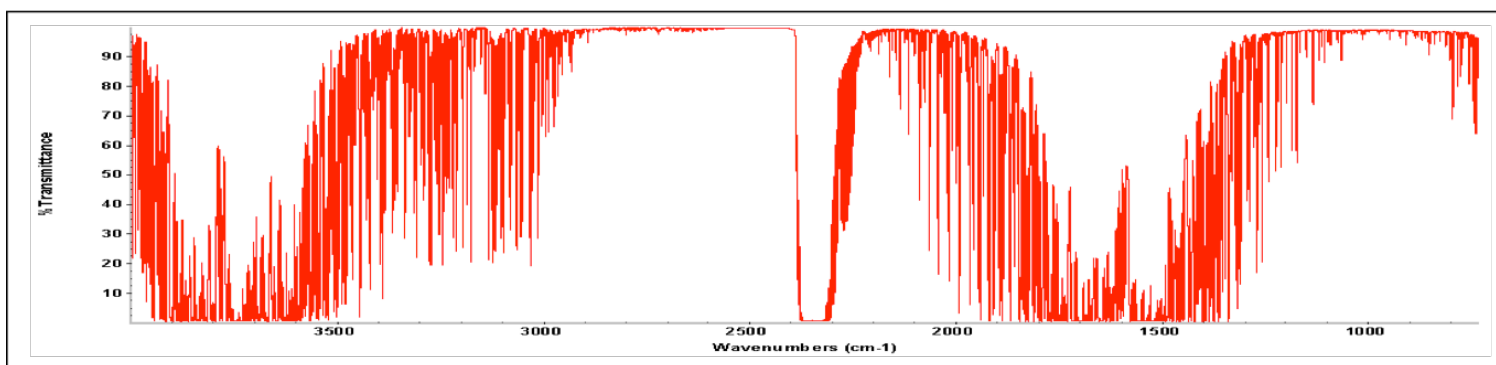


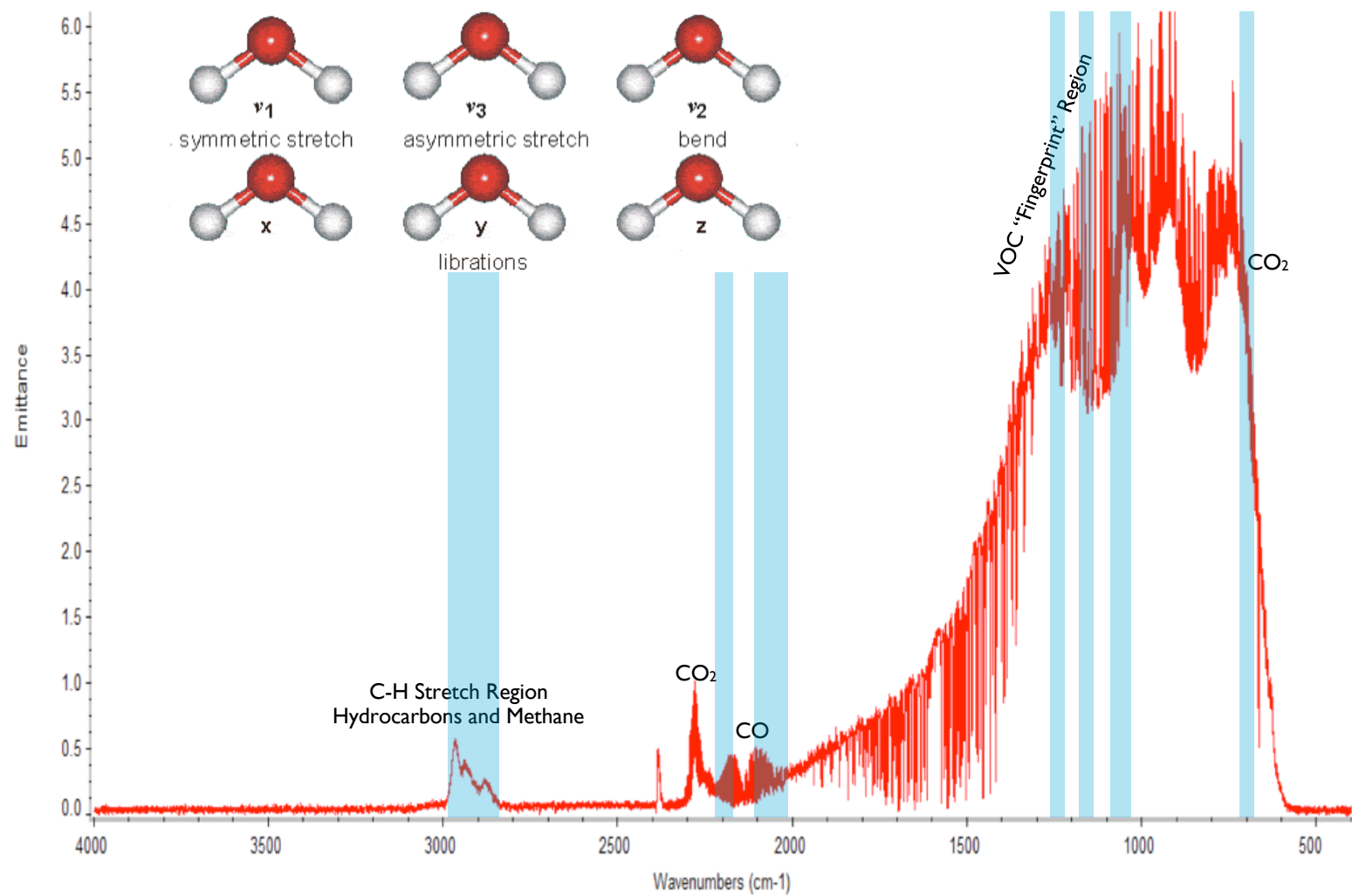
A mysterious vapor of unknown composition and concentration



Retroreflector

Transmission Spectrum





Flare Testing

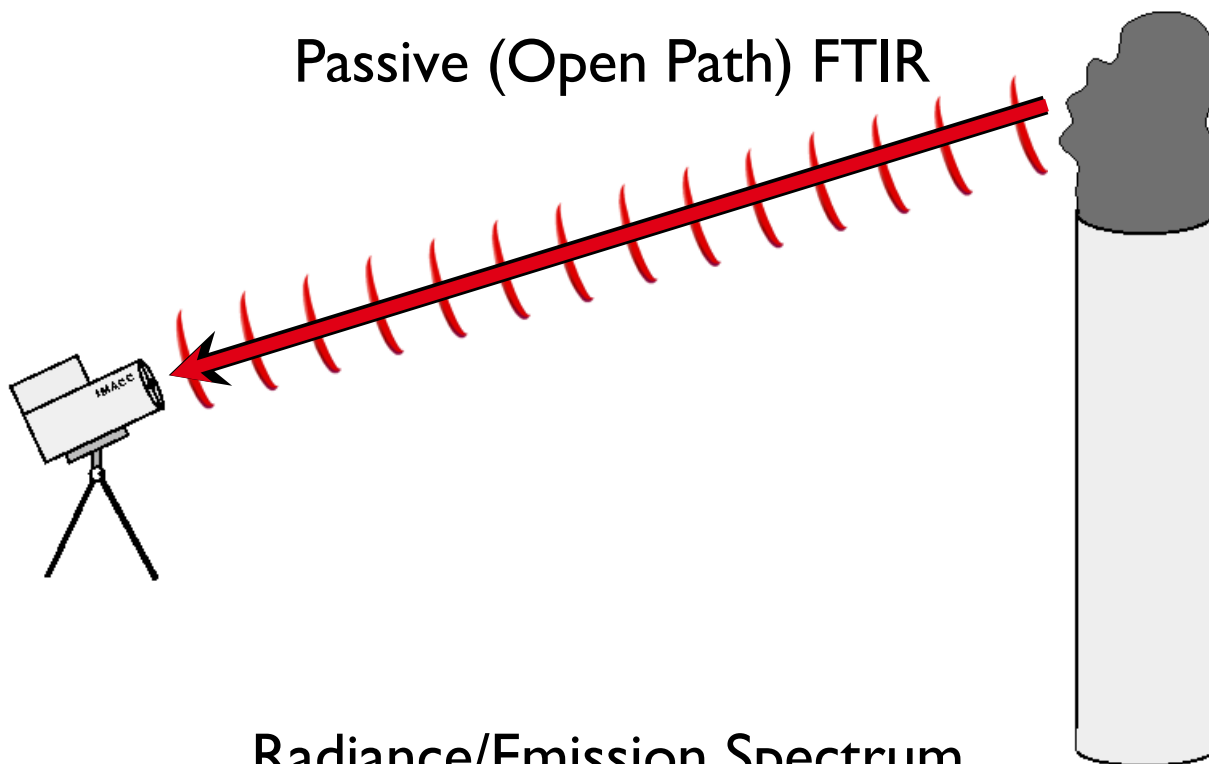


Flare Combustion Efficiency

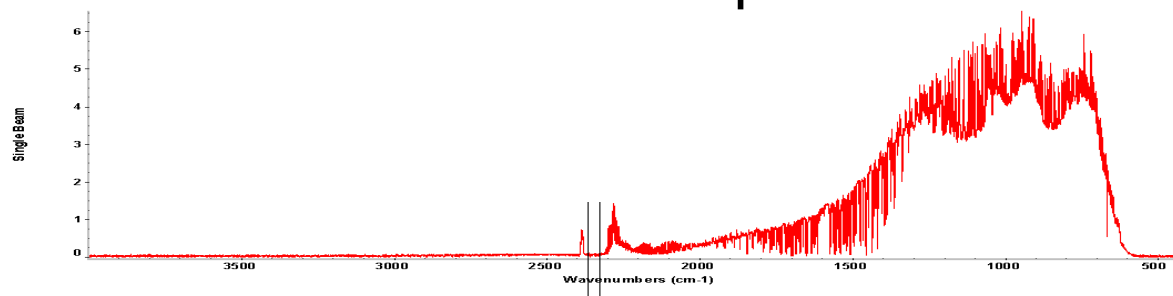
How efficiently does the flare convert hydrocarbons to carbon dioxide?

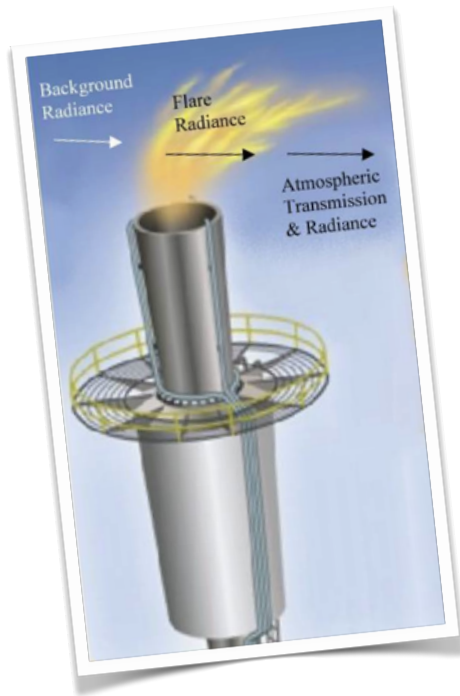
$$\frac{\text{Concentration of CO}_2 \text{ in the plume}}{\text{Concentration of CO}_2 + \text{CO} + \text{HC}}$$

Passive (Open Path) FTIR



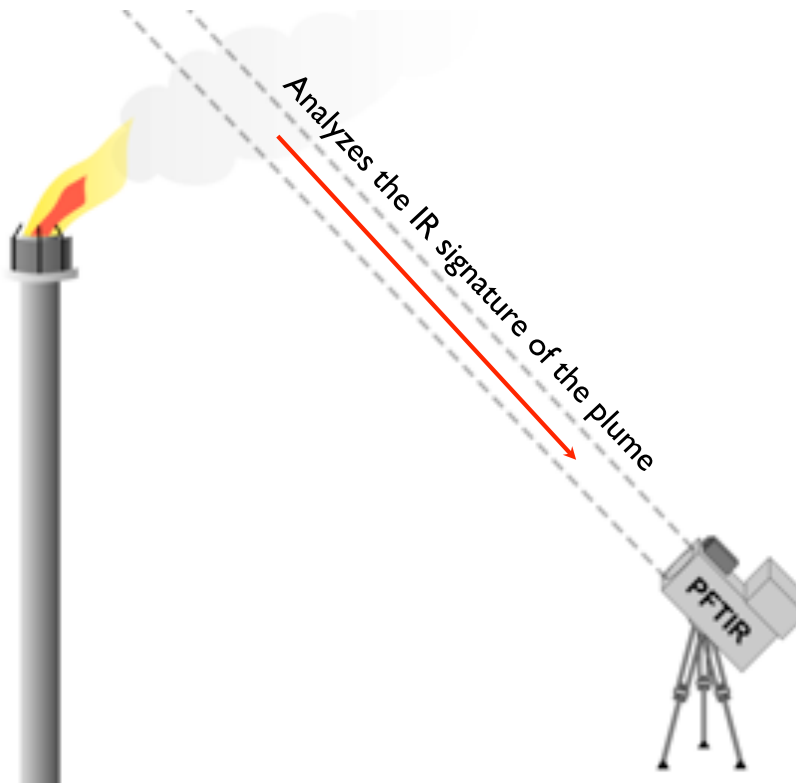
Radiance/Emission Spectrum





Total radiance to the instrument consists of many components.

Flare radiance is the only signal of concern.



Passive FTIR
No Active IR Source

Where
we aim



Fantastic. Why don't
you use PFTIR for
every source?

PFTIR has a
limitation...

The plume has to be hot!





DRONE

Noun

1. a low continuous humming sound or a dull monotonous tone

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2. a stingless male bee (as of the honeybee) that has the role of mating with the queen and does not gather nectar or pollen.
3. a person who lives on the labor of others; parasitic loafer.
4. any unmanned aircraft or ship that is guided remotely







Beyond Inspections

CUI support

Mapping and site integration

3D Modeling and scanning

LDAR – seal gap measurements

Emergency response

Emission testing





I don't have to test any
enclosed flares. Why
should I care?



What can we measure with FTIR?

✓ CO₂ - Method 3, 3A-B

✓ H₂O - Method 4

✓ SO₂ - Method 6, 6A-C

✓ NO_x - Method 7, 7A-E

✓ CO - Method 10, 10A-B

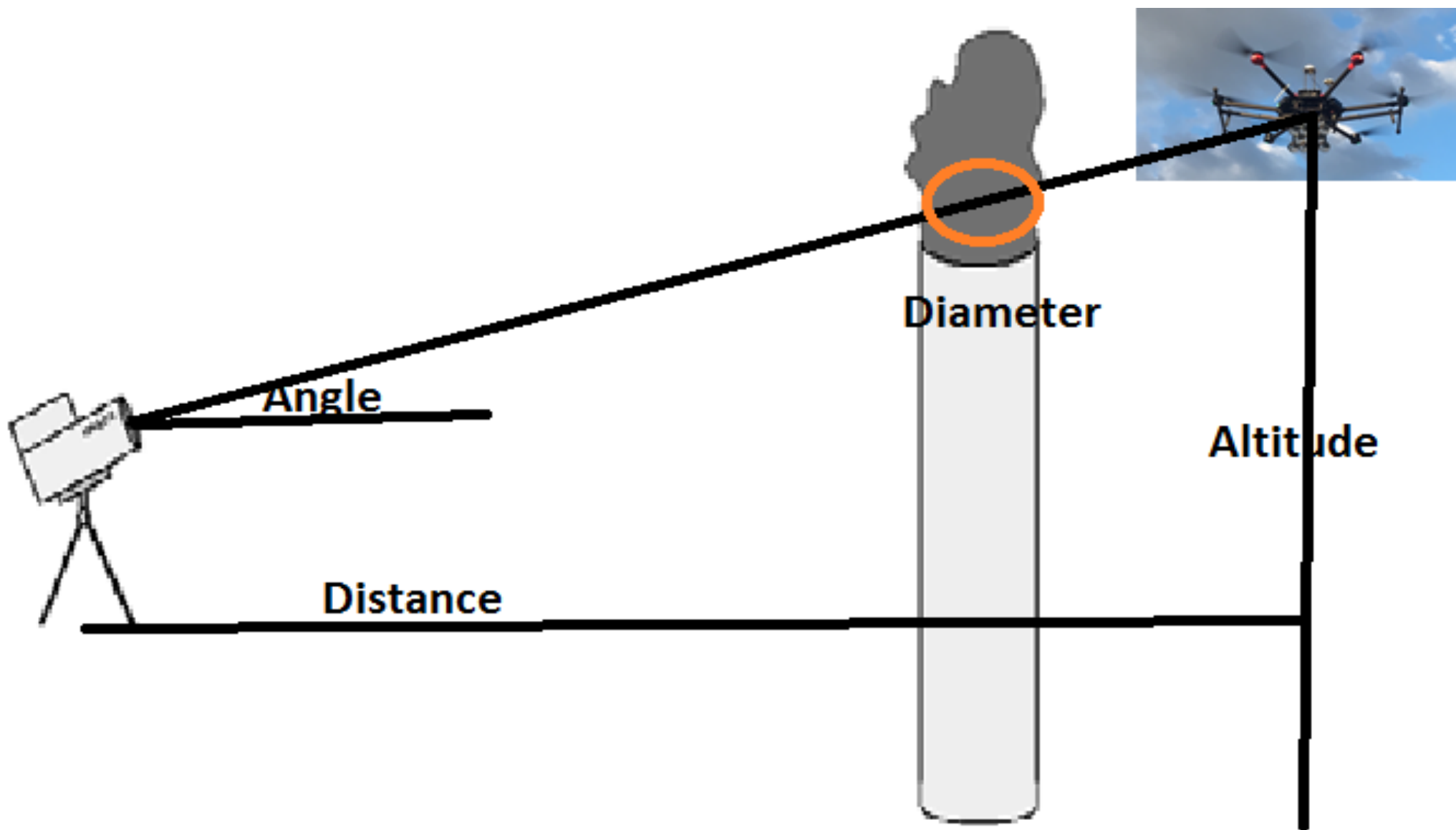
✓ VOCs - Method 18

✓ THC - Method 25, 25A-E

✓ HCl - Method 26, 26A

✓ NH₃ - CTM-027

✗ PM - Method 5, 5F, 201A, 202





What About Mass Emissions Measurement?

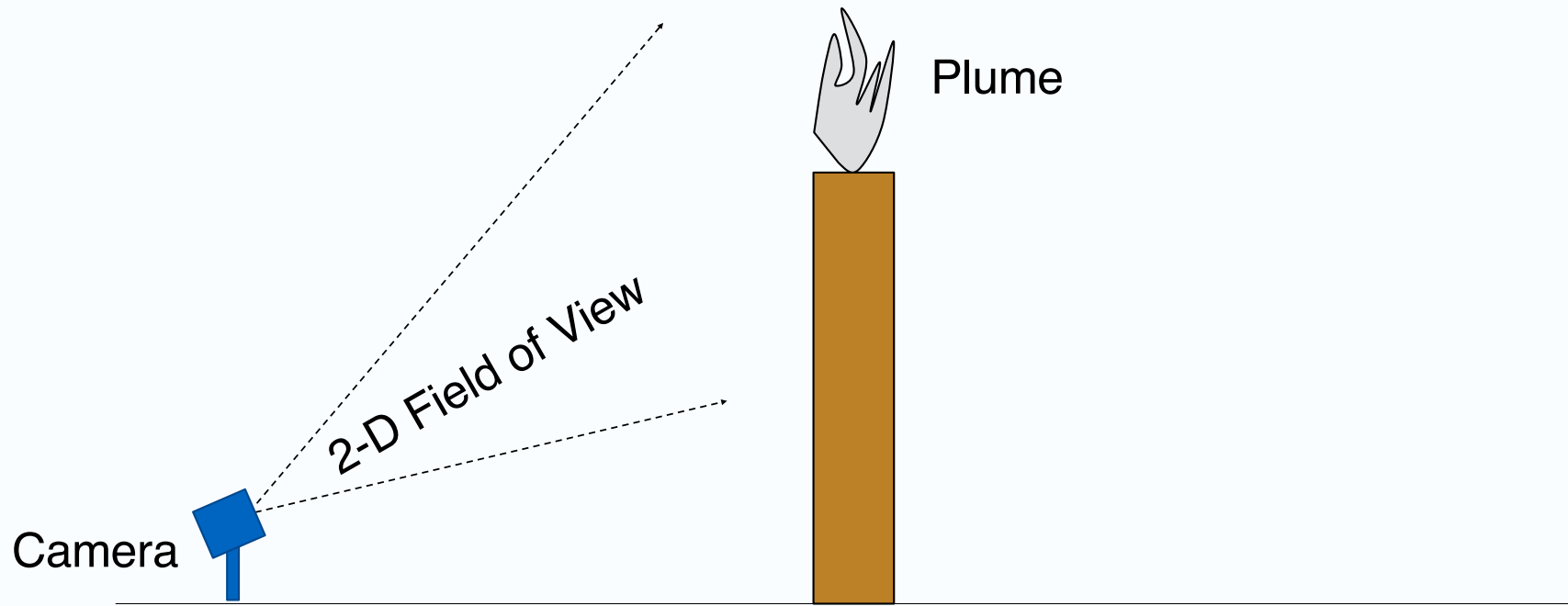
Gas Composition

Gas Flow Rate



Digital Image Correlation

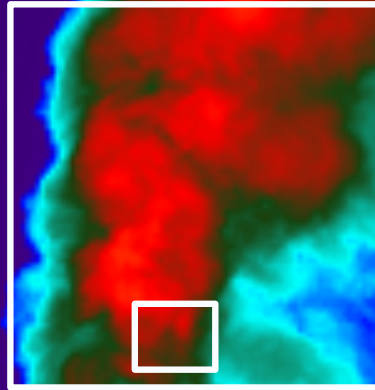
Remote Velocity Measurement



1. Take Pictures
2. Analyze Pictures
3. Calculate Plume Velocity

Image Preprocessing

Compare color intensities in subset
from first image to intensities in all
subsets on next image



Digital Image Correlation

Image 1

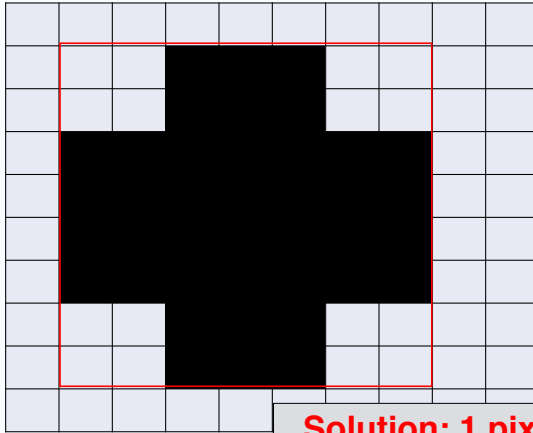
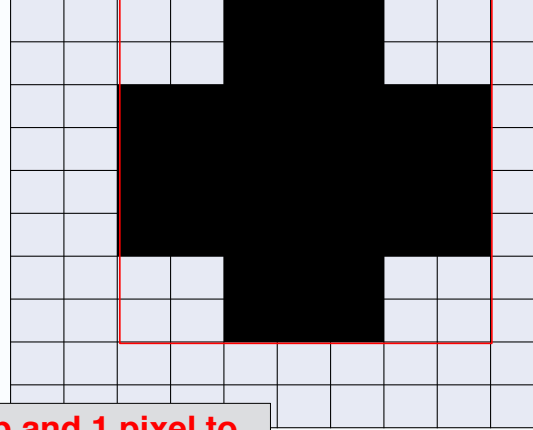


Image 2



Solution: 1 pixel up and 1 pixel to the right

0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	0
0	0	0	1	1	1	0	0	0	0
0	1	1	1	1	1	1	1	0	0
0	1	1	1	1	1	1	1	0	0
0	1	1	1	1	1	1	1	0	0
0	1	1	1	1	1	1	1	0	0
0	0	0	1	1	1	0	0	0	0
0	0	0	1	1	1	0	0	0	0
0	0	0	0	0	0	0	0	0	0

0	0	0	0	1	1	1	0	0	0
0	0	0	0	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0
0	0	1	1	1	1	1	1	1	0
0	0	1	1	1	1	1	1	1	0
0	0	1	1	1	1	1	1	1	0
0	0	0	0	1	1	1	0	0	0
0	0	0	0	1	1	1	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

Minimize:

$$\frac{\sum_x \sum_y [f(x+i, y+j) - \bar{f}][g(x, y) - \bar{g}]}{\sqrt{\sum_x \sum_y [f(x, y) - \bar{f}]^2 \sum_x \sum_y [g(x, y) - \bar{g}]^2}}$$

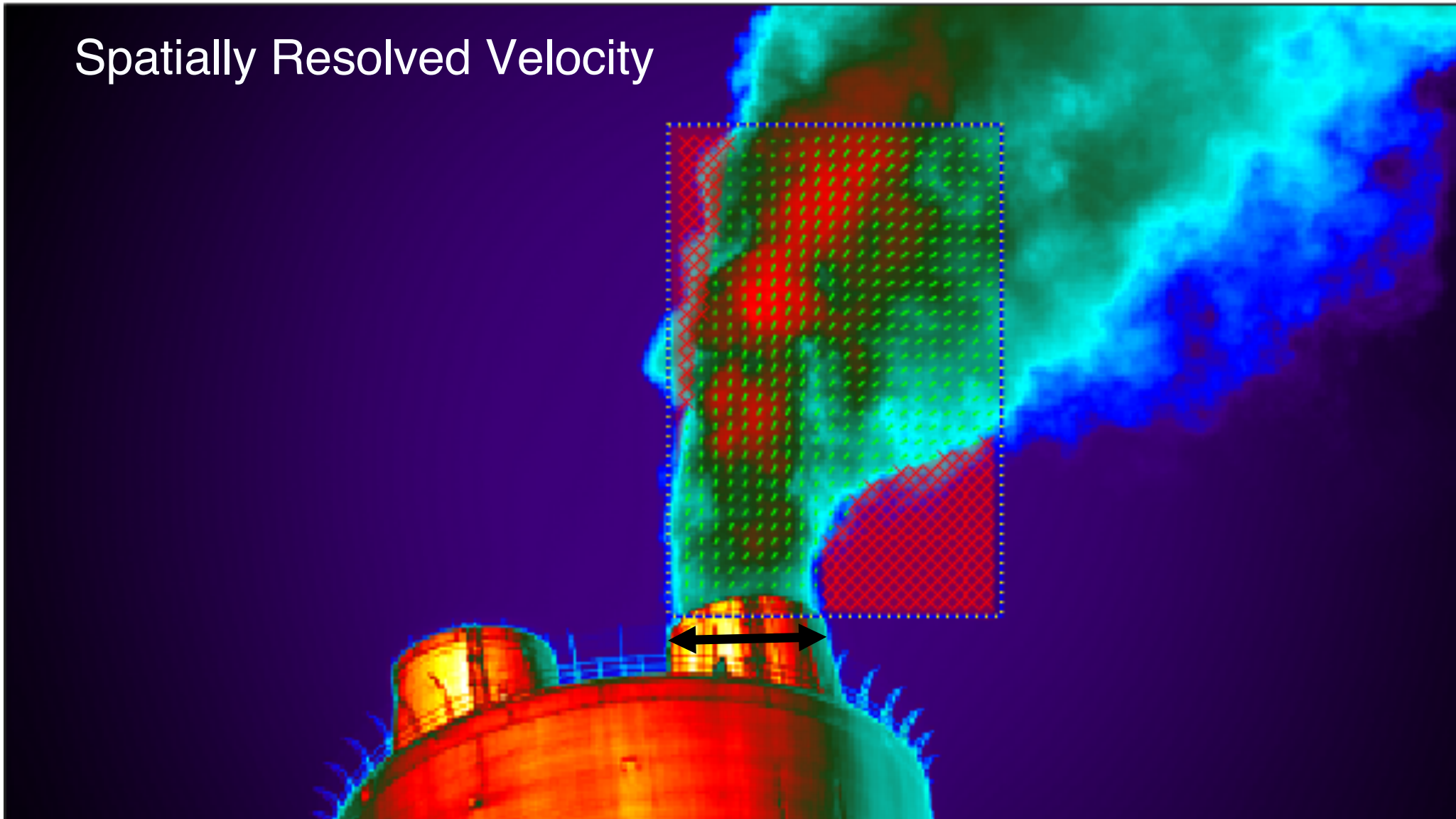
$g()$ = pixel intensity in image 1

$f()$ = is pixel intensity in image 2

\bar{g}, \bar{f} = mean intensity of subset

Solve for i and j

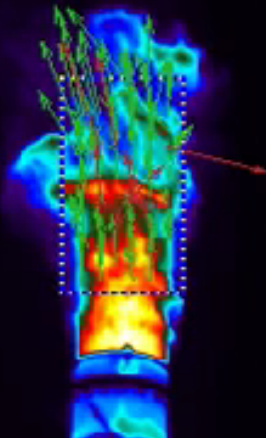
Spatially Resolved Velocity



PIVlab

Thielicke, W. and Stamhuis, E. J. (2014): PIVlab - Time-Resolved Digital Particle Image Velocimetry Tool for MATLAB (version: 1.41).

Analyzing... 95%



Analyze (CTRL+A)

Analyze current frame

Analyze all frames

Cancel

Clear all results

Frame progress: 33%
Interpolating velocity field
Total progress: 95%

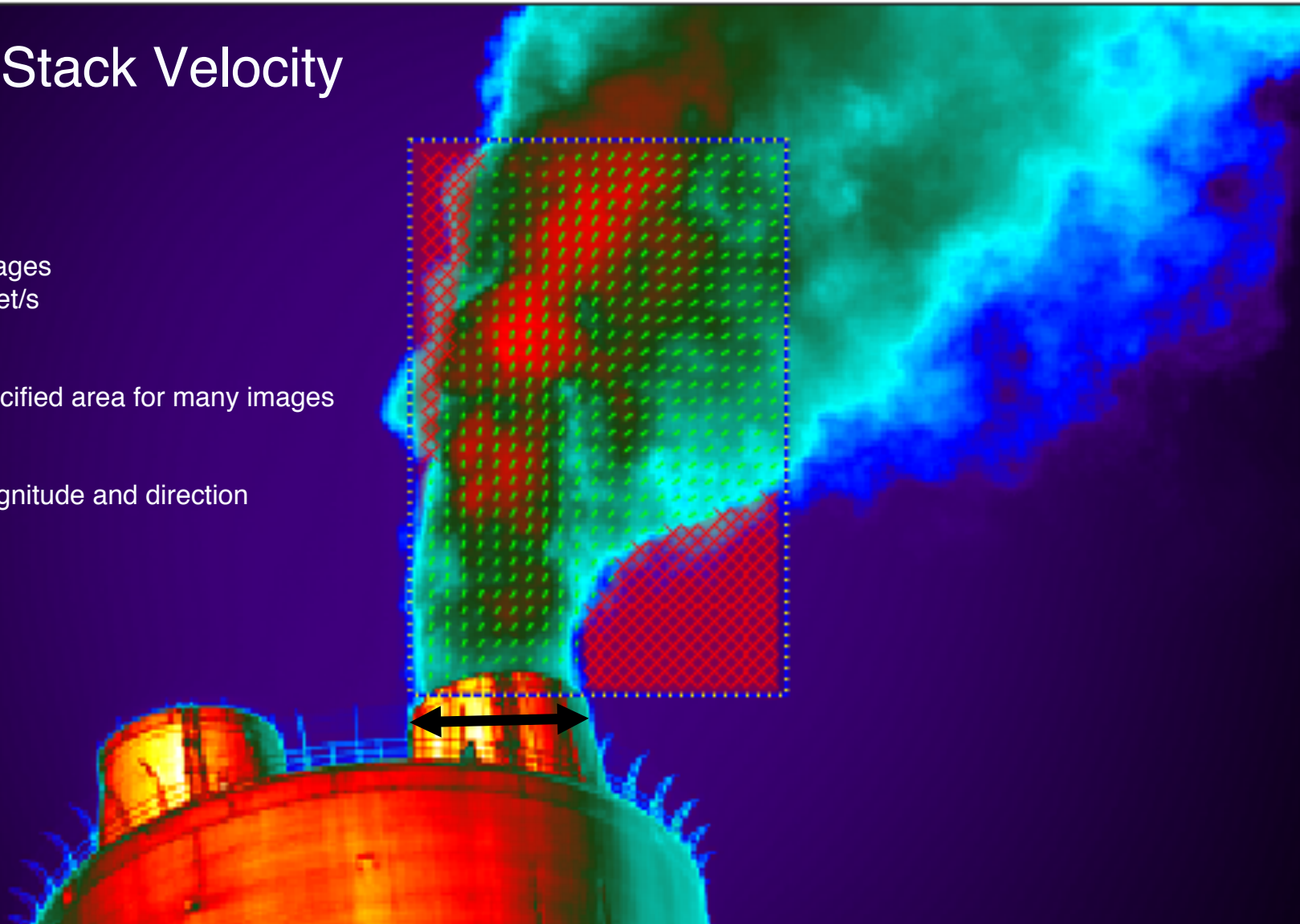
Time left: 00h 00m 35s

Average Stack Velocity

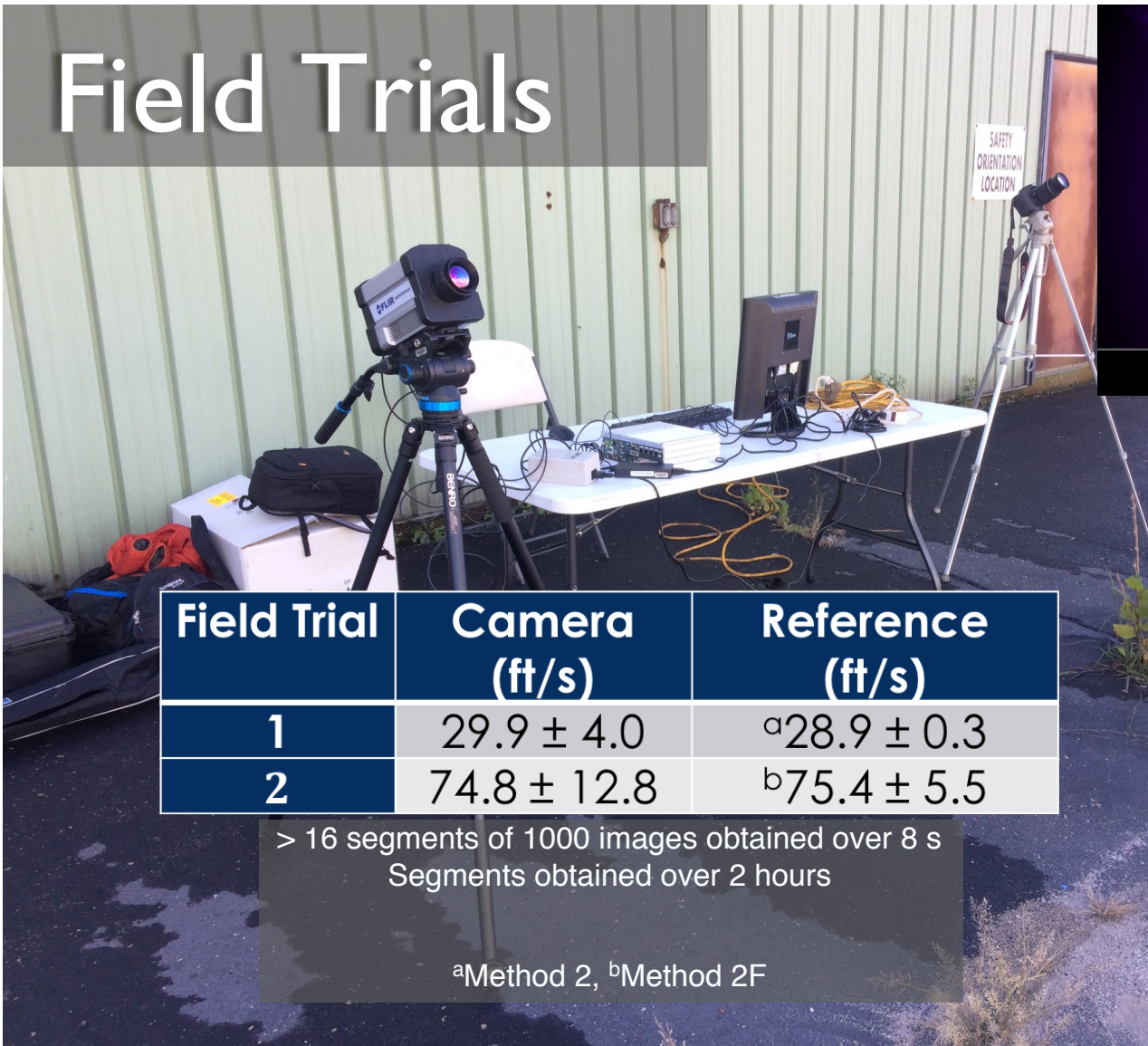
Identify stack diameter
Identify time between images
Convert pixel/frame to feet/s

Take average over a specified area for many images

End Result: Velocity magnitude and direction



Field Trials



Field Trial	Camera (ft/s)	Reference (ft/s)
1	29.9 ± 4.0	^a 28.9 ± 0.3
2	74.8 ± 12.8	^b 75.4 ± 5.5

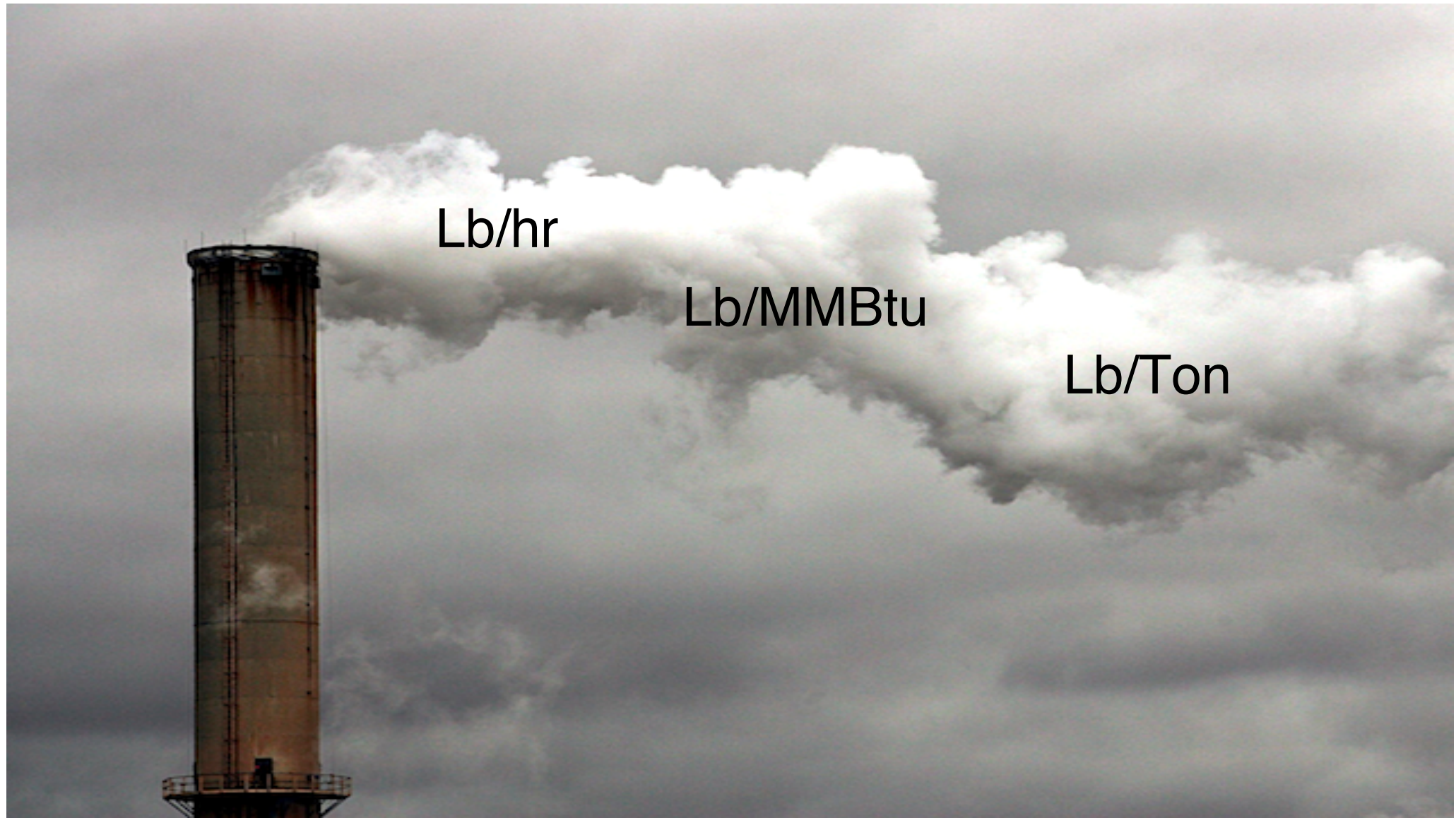
> 16 segments of 1000 images obtained over 8 s
Segments obtained over 2 hours

^aMethod 2, ^bMethod 2F



1344 x 784 pixels at 120 frames/s





Lb/hr

Lb/MMBtu

Lb/Ton

UAS Advantages

Increase in safety

UAS vs. standalone scaffolding

Decreasing costs

Reduced equipment needs and time on site

Quality Data

Flexible mounting solutions and real time control

UAS Specs

22 Minute average flight time

UAS runs at 66v

3D Printed gimbal mount

3D Printed mirror plate

Custom built mirror clusters

18 mph wind speed max

9 mph wind speed while
retaining quality data

Six motors for redundancy

Three GPSs for redundancy

Six batteries for redundancy



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